

SL7 GNSS Receiver



Powerful Satellite Tracking and Anti-jamming Capabilities

SatLab's unique design and self-developed antenna promise a stable and efficient operation. A highly integrated motherboard chip with low power consumption, supporting up to 1760 channels, tracks full constellations and frequencies. The excellent hardware configuration suppresses signal interference and obtains high-quality satellite-tracking data, ensuring performance and accuracy even in complex environments.





Visual Navigation Makes Stakeout Easier

Star-level HD camera provides users with immersive 3D visual navigation and stakeout experience. The featured AR stakeout on the Satsurv software provides guidance of the pointing arrow on the real scene and the real-time distance display to users for quickly locating the target point. And the AR function can also be performed in activities such as line stakeout and CAD-based map stakeout. The AR stakeout improves working efficiency by nearly 50% compared with the traditional graphics and text mode stakeout.

Accurate and Reliable Tilt Measurement

The SL7 utilizes SatLab's most advanced tilt measurement technology, and with built-in 200Hz IMU module and automatic initialization upon turning on can automatically complete the tilt calibration process without waiting for a fixed solution during operation. And it can measure and stakeout with survey-grade accuracy within a tilt compensation range of up to 60°, increasing efficiency by nearly 30%.





Longer Battery Life and Better Portability

Optimized the whole structure with new hardware, the nimble GNSS smart antenna weighs only 750g, Its energy-efficient hardware design ensures an extended operational battery life of up to 24 hours, allowing users to enjoy portability without worrying about battery drain.

Key Features



Applications

- Monitoring
- Land Survey
- Mapping
- Hydrographic
- Topography and As-built
- Agriculture



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Data Specifications

Channels	1408	1760
GNSS Signal ^[1]	GPS (L1C/A, L1C, L2P(Y), L2C, L5) BDS (B1I, B2I, B3I, B1C, B2a, B2b) GLONASS (L1, L2, L3) Galileo (E1, E5a, E5b, E6) QZSS (L1, L2, L5, L6*) NavIC (L5) SBAS (L1, L2, L5) PPP (B2b-PPP, Galileo E6-HAS)	GPS (L1C/A, L2C, L2P, L5) BDS (B1I, B1C, B2a, B2b, B2I, B GLONASS (L1CA, L2CA, L2P, L: Galileo (E1, E5a, E5b, E5 AltBor QZSS (L1C/A, L1S, L2C, L5) NavIC (L5) SBAS* (L1, L2, L5) PPP (B2b-PPP)
POSITIONING PERFORMANCE ^[2]		
High-precision static GNSS Surveying	H:2.5 mm + 0.1 ppm RMS / V:3.5 mm + 0.4 ppm RMS	
Static and East Static	U:2.5 mm + 0.5 ppm PMS / V:5 mm + 0.5 ppm PMS	

Static and Fast Static H:2.5 mm + 0.5 ppm RMS / V:5 mm + 0.5 ppm RMS H:8mm + 1 ppm RMS / V:15 mm + 1 ppm RMS Post Processing Kinematic

(PPK / Stop & Go) Initialization time: Typically 10 min for base and 5 min for rover

Initialization reliability: Typically>99.9%

B2b-PPP H: 10cm / V: 20cm

Code Differential GNSS Positioning H:±0.25 m+1 ppm RMS | V:±0.5 m+1 ppm RMS

SBAS: 0.5 m (H), 0.85 m (V)

H:8 mm+1ppm RMS / V:15 mm+1 ppm RMS Real Time Kinematic (RTK)

> Initialization time: Typically <10 s Initialization reliability: Typically > 99.9%

Time to first Fix Cold start: < 45 s | Hot start: < 30 s | Signal re-acquisition: < 2 s

Positioning rate 1 Hz, 5 Hz and 10 Hz

Hi-Fix[3] H: RTK+10mm / minute RMS | V: RTK+20mm / minute RMS Tilt Survey Performance[4] Additional horizontal pole-tilt uncertainty typically less than

8mm+0.7mm/°tilt(0° ~ 60°)1cm

AR stakeout accuracy

PHYSICAL

130mm × 68mm Dimensions (W x H) 0.75kg (1.65lb) Weight

-40°C~+75°C (-40°F~+167°F) Operation temperature Storage temperature $-55^{\circ}C \sim +85^{\circ}C (-67^{\circ}F \sim +185^{\circ}F)$

Humidity 100% non-condensing

Water/dustproof IP68 dustproof, protected from temporary immersion to

depth of 1.0m (3.28ft) MIL-STD-810G, 514.6

Free fall Designed to survive a 2m(6.56ft) natural fall onto concrete

ELECTRICAL

Internal Battery[5] Internal 7.2V / 6900mAh lithium-ion rechargeable battery

RTK rover(UHF/Cellular): up to 24 hours

using standard smartphone chargers or external power banks External power (Support 5V 2.8A Type-C USB external charging)

COMMUNICATION

Shock and vibration

I/O Interface 1 × USB type C port; 1 × SMA antenna port WiFi Frequency 2.4GHz, Supports 802.11 b/g/n

BT 5.2, 2.4GHz Bluetooth Near Field Communication for device touch pairing NFC

Power: 0.5W/1W/2W Adjustable Frequence: 410MHz~470MHz Internal UHF Radio Protocol: HI-TARGET, TRIMTALK450S, TRIMMARK III, SATEL-3AS,

TRANSEOT, etc.

Working Range: Typically 3~5km, optimal 8~15km

Channel: 116 (16 scalable)

CAMERA Professional star-level HD camera, large viewing angle, Function support AR stakeout

CONTROL PANEL

Physical button LED Lights

Satellite, Signal, Power

SYSTEM CONFIGURATION

Storage Output format 16GB ROM internal storage ASCII: NMEA-0183 Output rate 1Hz~20Hz Static data format Real Time Kinematic (RTK) GNS, Rinex RTCM3.X

Network Mode VRS, FKP, MAC, Support NTRIP protocol

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Note:

[1]SBAS service can be provided by rmware upgrade, PPP service is not available in all regions, check with your local sales representative for more information.

[2]The measurement accuracy, precision, reliability and initialization time depend on various factors, including tilt angle, number of satellites, geometric distribution, observation time, atmospheric conditions and multi-path validation, etc. The data are derived under normal conditions.

[3]Accuracies are dependent on GNSS satellite availability. Hi-Fix Positioning ends after 5 minutes without differential data.

[4]Irregular operations such as rapid rotation and high-intensity vibration may affect the inertial navigation accuracy.

[5]The battery operating time is related to the operating environment, operating temperature and battery life

Descriptions and Speci cations are subject to change without notice